

Section 7.3 : The Minimal Polynomial

Definition : Let T be a linear operator on a FDVS. A polynomial $p(t)$ is called a minimal polynomial of T if $p(t)$ is a monic polynomial of least positive degree for which $p(T) = O$ i.e. the zero operator.

Theorem 7.12 : Let $p(t)$ be a minimal polynomial of a linear operator T on a FDVS V .

(a): For any polynomial $g(t)$ if $g(T) = O$, then $p(t)$ divides $g(t)$. In particular $p(t)$ divides the characteristic polynomial of T .

(b): The minimal polynomial of T is unique.

Proof (a) : Let $g(t)$ be a polynomial for which $g(T) = O$.

By division algorithm, there exist polynomials $q(t)$ and $r(t)$ such that

$$g(t) = q(t) p(t) + r(t) \text{ where } r(t) = 0 \text{ or } \deg r(t) < \deg p(t).$$

$$\text{Then } g(T) = q(T) p(T) + r(T)$$

$$\text{i.e. } O = q(T) \cdot O + r(T)$$

which implies $r(T) = O$.

As $\deg r(t) < \deg p(t)$ and $p(t)$ is the minimal polynomial of T , so $r(t)$ must be zero.

Hence, $p(t)$ divides $g(t)$.

(b): Suppose that $p_1(t)$ and $p_2(t)$ are each minimal polynomials of T . Then $p_1(t)$ divides $p_2(t)$ by part (a). Since $p_1(t)$ and $p_2(t)$ have the same degree, we have $p_2(t) = c p_1(t)$ for some non zero scalar c . As $p_1(t)$ and $p_2(t)$ are monic, so $c = 1$. Hence $p_1(t) = p_2(t)$.

Definition : Let $A \in M_{n \times n}(F)$. The minimal polynomial $p(t)$ of A is the monic polynomial of least positive degree for which $p(A) = O$, i.e. the zero matrix.

Theorem 7.13 : Let T be a linear operator on a FDVS V and let β be an ordered basis for V . Then the minimal polynomial of T is the same as the minimal polynomial of $[T]_{\beta}$.

Corollary : For any $A \in M_{n \times n}(F)$, the minimal polynomial of A is the same as the minimal polynomial of L_A .

Theorem 7.14 : Let T be a linear operator on a FDVS V and let $p(t)$ be the minimal polynomial of T . A scalar λ is an eigenvalue of T if and only if $p(\lambda) = 0$. Hence the characteristic polynomial and the minimal polynomial of T have the same zeros.

Proof : Let $f(t)$ be the characteristic polynomial of T . Since $p(t)$ divides $f(t)$, there exist polynomials $q(t)$ and $r(t)$ such that $f(t) = q(t) p(t)$.

If λ is a zero of $p(t)$ then $f(\lambda) = q(\lambda) p(\lambda) = q(\lambda) \cdot 0 = 0$. So λ is a zero of $f(t)$ i.e. λ is an eigenvalue of T .

Conversely, suppose λ is an eigenvalue of T and let $x \in V$ be an eigenvector corresponding to λ . Then $T(x) = \lambda x$ and $p(T)(x) = p(\lambda)x$. As $p(T) = O$ so $0 = O(x) = p(T)(x) = p(\lambda)x$. Since x being an eigenvector is nonzero, it follows that $p(\lambda) = 0$ and so λ is a zero of $p(t)$ also.

Corollary : Let T be a linear operator on a FDVS V with minimal polynomial $p(t)$ and characteristic polynomial $f(t)$. Suppose that $f(t)$ factors as

$$f(t) = (\lambda_1 - t)^{n_1} (\lambda_2 - t)^{n_2} \dots (\lambda_k - t)^{n_k}$$

where $\lambda_1, \lambda_2, \dots, \lambda_k$ are the distinct eigenvalues of T . Then there exist integers m_1, m_2, \dots, m_k such that $1 \leq m_i \leq n_i$ for all $i = 1, 2, \dots, k$, and

$$p(t) = (\lambda_1 - t)^{m_1} (\lambda_2 - t)^{m_2} \dots (\lambda_k - t)^{m_k}$$

Example 1 : Compute the minimal Polynomial of the matrix

$$A = \begin{pmatrix} 3 & -1 & 0 \\ 0 & 2 & 0 \\ 1 & -1 & 2 \end{pmatrix}$$

Sol. : The characteristic polynomial of A is $\det(A - tI)$

$$\text{i.e.} \quad \det \begin{pmatrix} 3-t & -1 & 0 \\ 0 & 2-t & 0 \\ 1 & -1 & 2-t \end{pmatrix} \quad \text{i.e.} \quad f(t) = -(t-2)^2(t-3)$$

As the minimal polynomial $p(t)$ divides $f(t)$ and they have the same zeros, so possibilities for $p(t)$ are

$$(t-2)(t-3) \quad \text{or} \quad (t-2)^2(t-3)$$

If we let $p(t) = (t-2)(t-3)$ then $p(A) = (A-2I)(A-3I) = A^2 - 5A + 6I = O$.

Thus $p(t)$ is a polynomial of least degree satisfying $p(A) = O$, so the minimal polynomial of A is $p(t) = (t-2)(t-3)$.

Example 2 : Let T be the linear operator on \mathbb{R}^2 defined by $T(a, b) = (2a+5b, 6a+b)$. Compute minimal polynomial of T .

Sol. : Let β be standard ordered basis for \mathbb{R}^2 . Then $[T]_{\beta} = \begin{pmatrix} 2 & 5 \\ 6 & 1 \end{pmatrix}$. The characteristic polynomial of T is $f(t) = \begin{vmatrix} 2-t & 5 \\ 6 & 1-t \end{vmatrix} = (t-7)(t+4)$.

As characteristic polynomial and minimal polynomial have the same zeros, therefore the minimal polynomial is also $(t-7)(t+4)$.

Example 3. : Let D be the linear operator on $P_2(\mathbb{R})$ defined by $D(g(x)) = g'(x)$. Compute the minimal polynomial of D .

Sol. : Let $\beta = \{1, x, x^2\}$ be standard ordered basis for $P_2(\mathbb{R})$. Then $[D]_{\beta} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{pmatrix}$.

The characteristic polynomial of D is $-t^3$.

The possibilities for minimal polynomial are t, t^2, t^3 .

As $D \neq O$ and $D^2 \neq O$ but $D^3 = O$. Therefore the minimal polynomial of D is t^3 .

Theorem 7.15 : Let T be a linear operator on an n -dimensional vector space V such that V is a T -cyclic subspace of itself. Then the characteristic polynomial $f(t)$

and the minimal polynomial $p(t)$ have the same degree, and hence $f(t) = (-1)^n p(t)$.

Proof : Since V is a T -cyclic space, \exists a nonzero $x \in V$ such that

$\beta = \{ x, T(x), \dots, T^{n-1}(x) \}$ is a basis for V . (By Theorem 5.22).

Let $g(t) = a_0 + a_1 t + \dots + a_k t^k$ be a polynomial of degree $k < n$. Then $a_k \neq 0$

and $g(T)(x) = a_0 x + a_1 T(x) + \dots + a_k T^k(x)$.

Observe that $g(T)(x)$ is a linear combination of elements of β such that $a_k \neq 0$.

Then $g(T)(x) \neq 0$. (Since β is linearly independent). Hence $g(T) \neq O$.

Therefore, the minimal polynomial of T has degree n which is also the degree of the characteristic polynomial. Hence, $f(t) = (-1)^n p(t)$.

Theorem 7.16 : Let T be a linear operator on a FDVS V . Then T is diagonalizable

if and only if the minimal polynomial of T is of the form

$$p(t) = (t - \lambda_1)(t - \lambda_2)\dots\dots\dots(t - \lambda_k)$$

where $\lambda_1, \lambda_2, \dots, \lambda_k$ are the distinct eigenvalues of T .

Proof : Not to be done.

Example 4 : Determine all matrices $A \in M_{2 \times 2}(\mathbb{R})$ for which $A^2 - 3A + 2I = O$.

Sol. : Let $g(t) = t^2 - 3t + 2 = (t - 1)(t - 2)$.

As $g(A) = A^2 - 3A + 2I = O$, the minimal polynomial $p(t)$ of A divides $g(t)$.

Hence the possibilities for $p(t)$ are $t - 1$ or $t - 2$ or $(t - 1)(t - 2)$.

If $p(t) = t - 1$ then $A = I$ satisfies the given condition.

If $p(t) = t - 2$ then $A = 2I$ satisfies the given condition.

If $p(t) = (t - 1)(t - 2)$ then A is diagonalizable with eigenvalues 1 and 2

and hence A is similar to $\begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$.

Example 5 : Let $A \in M_{n \times n}(\mathbb{R})$ satisfy $A^3 = A$. Show that A is diagonalizable .

Sol. : Let $g(t) = t^3 - t = t(t-1)(t+1)$. Then $g(A) = O$ and hence the minimal polynomial $p(t)$ of A divides $g(t)$. Hence the possibilities for $p(t)$ are t , $t-1$ or $t+1$ or $t(t-1)$ or $t(t+1)$ or $(t-1)(t+1)$ or $t(t-1)(t+1)$. In each of these possibilities $p(t)$ has no repeated factors . Thus A is diagonalizable (by Theorem 7.16).

Example 6 : In example 3 we have seen that the minimal polynomial of differential operator D is t^3 . Thus it has repeated zeros. So by Theorem 7.16, D is not diagonalizable.

Assignment : Do questions 5, 8 and 10 from exercise 7.3 .